



Call for Papers

ISRR 2026

November 16-20, 2026

Malacca, Malaysia



Website

www.isrr2026.su.domains/



Organizing Committee

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The ISRR Symposia have a tradition of convening prominent robotics researchers and pioneers from academia, government, and industry to evaluate and exchange their perspectives and ideas on the current state of robotics and explore promising new directions for future research. Each edition of the symposium is single-track and highly interactive. Attendees actively participate in all sessions to foster stimulating and dynamic discussions. As the flagship symposium of the International Foundation of Robotics Research (IFRR), the 2026 edition of ISRR will continue the tradition of exceptional gatherings.

The Symposium will take place in a relaxed atmosphere, with a limited number of attendees to foster close technical and personal interactions. Over the course of three days following a single-track format, and submissions covering all areas of robotics research are welcome. Sessions will be organized thematically, with ample time for discussion. The ISRR 2026 will be held in Malacca, Malaysia a city rich in culture and history, at the Casa Del Rio Malacca Hotel.

Important Dates

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| • Paper Submission Deadline | May 15, 2026 May 31, 2026 |
| • Decision | July 15, 2026 August 1, 2026 |
| • Revised Submission | September 15, 2026 |
| • Event | November 16 – 20, 2026 |

Topics include but not limited to:

- Simultaneous Localization and Mapping (SLAM) and 3D Perception
- Field Robotics (Underwater, Space, and Aerial Exploration)
- Human-Robot Interaction (HRI) and Collaborative Robotics
- Algorithmic Foundations (Geometry, Topology, and Motion Planning)
- Model-Based vs. Data-Driven Control (Physics vs. Machine Learning)
- Legged Locomotion (Humanoids and Quadrupeds)
- Medical and Rehabilitation Robotics (Exoskeletons and Haptics)
- Soft Robotics and Bio-inspired Design
- Micro and Nano-Robotics
- Distributed Systems and Multi-Robot Swarms
- Ethical, Social, and Economic Impacts of Autonomous Systems
- Experimental Validation and Reproducibility in Robotics Research



Contact Us

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